

SHIMADEN MR13/FP93

Supported Series: MR13, FP93 devices

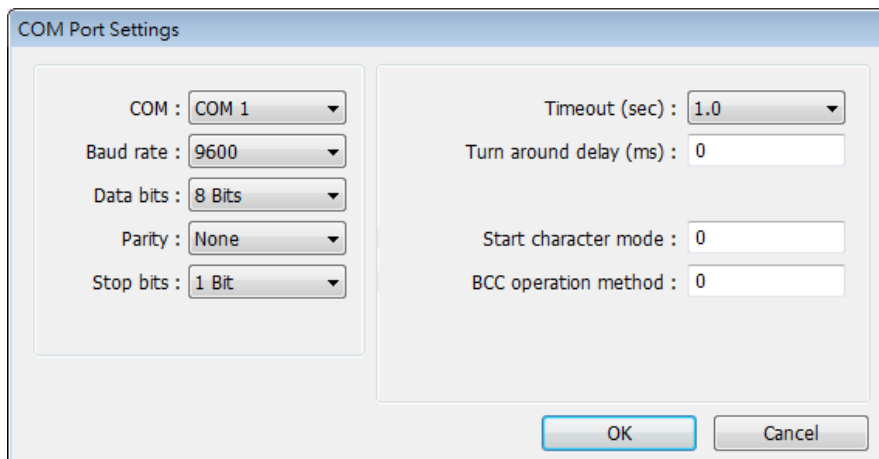
Website: <http://www.shimaden.co.jp>

HMI Setting:

Parameters	Recommended	Options	Notes
PLC type	SHIMADEN MR13/FP93		
PLC I/F	RS485 2W		
Baud rate	9600	1200-19200	
Data bits	7	7 or 8	
Parity	E	None/Even	
Stop bits	1	1	
PLC sta. no.	1	1~255	
Start Character Mode	Select 3 : @_:_CR	0, 1 : STX_ETX_CR 2 : STX_ETX_CR LF 3 : @_:_CR	For FP93, select 0,1
BCC Operation Method	Select 3 : XOR	0, 1 : Addition 2 : Addition +2's complement 3 : XOR 4 : None	

Note :

Address 018C is a communication control register, only when it is set to 1 can this register be allowed to write to other registers.



COM Port Settings

COM : COM 1

Baud rate : 9600

Data bits : 8 Bits

Parity : None

Stop bits : 1 Bit

Timeout (sec) : 1.0

Turn around delay (ms) : 0

Start character mode : 0

BCC operation method : 0

OK Cancel

Device Address:

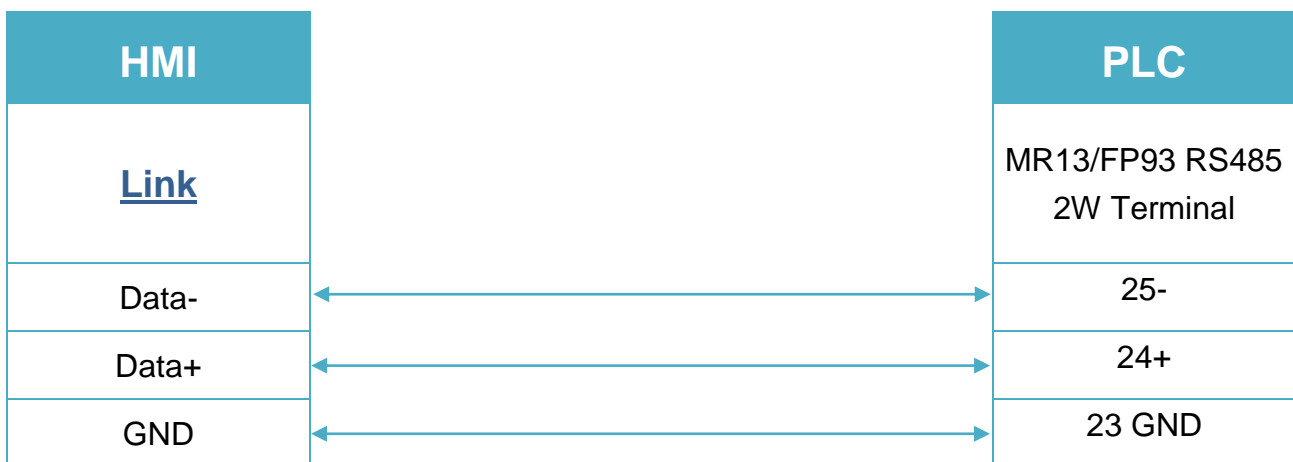
Bit/Word	Device	Format	Range	Memo
W	Channel 1	HHHH	0 ~ ffff	Read/Write 1st Channel Register
W	Channel 2	HHHH	0 ~ ffff	Read/Write 2nd Channel Register
W	Channel 3	HHHH	0 ~ ffff	Read/Write 3rd Channel Register

Wiring Diagram:

Diagram 1

RS-485 2W

The serial port pin assignments may vary between HMI models, please click the following link for more information.



MR13 Communication Parameter Settings

Data Address	Parameter	Details of Parameter	R /W
0100	PV Value	Within measuring range	R
0101	E_SV Execution SV Value	Within setting range	R
0102	OUT Control Output Value	Within range 0.0~100.0%	R
0103	Reserved		
0104	Action Flag	(See detailed explanation below.)	R
0105	Event Output Flag	(See detailed explanation below.)	R
0106	Reserved		
0107	Reserved		
0108	REM Value	Within setting range	R
0109	Reserved		

010A	Reserved		
010B	DI Input State Flag	(See detailed explanation below.)	R
Data Address (hex)	Parameter	Details of Parameter	R /W
0111	RANGE	Refer to the measuring range code list.	R
0112	Reserved		
0113	DP Decimal Point	Position of decimal point (0:Without decimal point 1:With decimal point)	R
0114	PV Sc_L Lower Limit	For Linear Input:-1999~9999 unit For Thermocouple, and RTD Input: Measuring range to be displayed.	R
0115	PV Sc_H Higher Limit		R

Data Address (hex)	Parameter	Details of Parameter	R/W
0120	E_PRG	Program Action Flag	R
0121	Reserved		
0122	Reserved		
0123	E_PRT	The number of execution patterns (When program is reset, value=7FFEh)	R
0124	E_STP	Execution step number (When program is reset, value=7FFEh)	R
0125	E_TIM	Remaining time of execution step (When program is reset, value=7FFEh)	R
0126	E_PID	Execution PID number (When program is reset, value=7FFEh)	R

Data Address	Parameter	Details of Parameter	R/W
0184	AT Auto Tuning	0:No execution 1:Execution	W
018C	Operation	0:Local 1:COM	W

0190	PROG RUN/RST Program Run/Reset	0 : RST, 1 : RUN (Writing is possible only in CH1)	W
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0191	PROG HLD Program Hold	0 : Release, 1 : HLD (Writing is possible only in CH1)	W
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0300	SV	Local SV Value, within set value limiter	R/W
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Data Address	Parameter	Details of Parameter	R/W
030A	SV Limt_L Lower Limit	Within measuring range, On condition that SV Limt_L < SV Limt_H	R/W
030B	SV Limt_h Higher Limit		

0314	REM SC_L	Within measuring range On condition that REM SC_L \neq REM SC_H	R/W
0315	REM SC_H		
0316	REM Bias	Range: -1999~5000 unit	R/W
0317	REM Filt	Range: 0~100 seconds	R/W

031A	REM-CH	Remote channel assignment 0 : OFF , 1 : CH1 , 2 : CH2 , 3 : CH3	R/W
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Data Address	Parameter	Details of Parameter	R/W
0320	SV Follow SW	CH2 & CH3 SV follow setting flag 1: Follow 0:No	R/W
0321	SV Follow	Follow type deviation SV set value: 1999~5000 unit	R/W

0400	FIX P	Control Output Proportional Baud Range: 0.0~999.9%(0.0:OFF)	R/W
0401	FIX I	Control Output Integral Time Range: 0~6000 Seconds (0.0:OFF)	R/W

0402	FIX D	Control Output Derivative Time Range 0~3600 Seconds (0.0:OFF)	R/W
0403	FIX MR	Manual Reset Range: -50.0~50.0%	R/W
0404	FIX DF	Hysteresis Range: 1~999 unit	R/W
0405	FIX OUT Limt_L	Control Output Lower Limit Output Limiter Range: 0.0~99.9%	R/W
0406	FIX OUT Limt_H	Control Output Higher Limit Output Limiter Range: 0.1~100.0%	R/W
0407	FIX SF	Control Output Target Value Function Range: OFF , 0.01~1.00	R/W
0408	Prog P1	PROG mode PB1 Range: 0.0~999.9% (0.0:OFF)	R/W
0409	Prog I1	PROG mode IT1 Range: 0~6000 seconds (0.0:OFF)	R/W
040A	Prog D1	PROG mode DT1 Range: 0~3600 seconds (0.0:OFF)	R/W
040B	Prog MR1	PROG mode MR1 Range: -50.0~50.0%	R/W
040C	Prog DF1	PROG mode DF1 Range: 1~999 unit	R/W
040D	Prog O_Lmt_L1	PROG mode lower limit side output limiter 1 Range: 0.0~99.9%	R/W
040E	Prog O_Lmt_H1	PROG mode higher limit side output limiter 1 Range: 0.1~100.0%	R/W
040F	Prog SF1	PROG mode target value function 1 Range: OFF,0.01~1.00	R/W
0410	Prog P2	PROG mode PB2 Range: 0.0~999.9% (0.0:OFF)	R/W
0411	Prog I2	PROG mode IT2 Range: 0~6000 seconds (0.0:OFF)	R/W
0412	Prog D2	PROG mode DT2 Range: 0~3600 seconds (0.0:OFF)	R/W
0413	Prog MR2	PROG mode MR2 Range: -50.0~50.0%	R/W
0414	Prog DF2	PROG mode DF2 Range: 1~999 unit	R/W
0415	Prog O_Lmt_L2	PROG mode lower limit side output limiter 2 Range: 0.0~99.9%	R/W

0416	Prog O_Lmt_H2	PROG mode higher limit side output limiter 2 Range: 0.1 ~ 100.0%	R/W
0417	Prog SF2	PROG mode target value function 2 Range: OFF,0.01 ~ 1.00	R/W
0418	Prog P3	PROG mode PB3 Range: 0.0 ~ 999.9% (0.0:OFF)	R/W
0419	Prog I3	PROG mode IT3 Range: 0 ~ 6000 seconds (0.0:OFF)	R/W
041A	Prog D3	PROG mode DT3 Range: 0 ~ 3600 seconds (0.0:OFF)	R/W
041B	Prog MR3	PROG mode MR3 Range: -50.0 ~ 50.0%	R/W
041C	Prog DF3	PROG mode DF3 Range: 1 ~ 999 unit	R/W
041D	Prog O_Lmt_L3	PROG mode lower limit side output limiter 3 Range: 0.0 ~ 99.9%	R/W
041E	Prog O_Lmt_H3	PROG mode higher limit side output limiter 3 Range: 0.1 ~ 100.0%	R/W
041F	Prog SF3	PROG mode target value function 3 Range: OFF,0.01 ~ 1.00	R/W

0500	EV1_MODE	0:Not assigned 1:Higher limit deviation value 2:Lower limit deviation value 3:Out of range between higher & lower limits 4:Within range between higher & lower limits 5:Higher limit absolute value 6:Lower limit absolute value 7:Scaleover 8:Program RUN 9:Program END 10:Program STEP Only when Subaddress=EV1_CH.	R/W
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0501	EV1 Set Point	<ol style="list-style-type: none"> 1. Higher limit deviation value alarm: 0~1999 unit 2. Lower limit deviation value alarm: 0~-1999 unit 3. Out of range between higher & lower limits value alarm: 0~1999 unit 4. Within range between higher and lower limits value alarm: 0~1999 unit 5. Higher limit absolute value alarm: Within measuring range 6. Lower limit absolute value alarm: Within measuring range Only when Subaddress=EV1_CH.	R/W
0502	EV1 Diffrent	Alarm hysteresis 1~999 unit Only when Subaddress=EV1_CH.	R/W
0503	EV1 Inhibit	Alarm stand by 1~4 Only when Subaddress=EV1_CH.	R/W
0504	EV1 Delay	Alarm delay time 0~9999 seconds Only when Subaddress=EV1_CH.	R/W

0506	EV1_CH	Channel number setting 1:CH1, 2:CH2, 3:CH3	R/W
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0510	EV2_MODE	<ol style="list-style-type: none"> 0:Not assigned 1:Higher limit deviation value 2:Lower limit deviation value 3:Out of range between higher & lower limits 4:Within range between higher & lower limits 5:Higher limit absolute value 6:Lower limit absolute value 7:Scaleover 8:Program RUN 9:Program END 10:Program STEP Only when Subaddress=EV2_CH.	R/W
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0511	EV2 Set Point	1. Higher limit deviation value alarm: 0~1999 unit 2. Lower limit deviation value alarm: 0~-1999 unit 3. Out of range between higher & lower limits value alarm: 0~1999 unit 4. Within range between higher and lower limits value alarm: 0~1999 unit 5. Higher limit absolute value alarm: Within measuring range 6. Lower limit absolute value alarm: Within measuring range Only when Subaddress=EV2_CH.	R/W
0512	EV2 Diffrent	Alarm hysteresis 1~999 unit Only when Subaddress=EV2_CH.	R/W
0513	EV2 Inhibit	Alarm stand by 1~4 Only when Subaddress=EV2_CH.	R/W
0514	EV2 Delay	Alarm delay time 0~9999 seconds Only when Subaddress=EV2_CH.	R/W
0516	EV2_CH	Channel number setting 1:CH1, 2:CH2, 3:CH3	R/W
0520	EV3_MODE	0:Not assigned 1:Higher limit deviation value 2:Lower limit deviation value 3:Out of range between higher & lower limits 4:Within range between higher & lower limits 5:Higher limit absolute value 6:Lower limit absolute value 7:Scaleover 8:Program RUN 9:Program END 10:Program STEP Only when Subaddress=EV3_CH.	R/W

0521	EV3 Set Point	1. Higher limit deviation value alarm: 0~1999 unit 2. Lower limit deviation value alarm: 0~-1999 unit 3. Out of range between higher & lower limits value alarm: 0~1999 unit 4. Within range between higher and lower limits value alarm: 0~1999 unit 5. Higher limit absolute value alarm: Within measuring range 6. Lower limit absolute value alarm: Within measuring range Only when Subaddress=EV3_CH	R/W
0522	EV3 Diffrent	Alarm hysteresis 1~999 unit Only when Subaddress=EV3_CH.	R/W
0523	EV3 Inhibit	Alarm stand by 1~4 Only when Subaddress=EV3_CH.	R/W
0524	EV3 Delay	Alarm delay time 0~9999 seconds Only when Subaddress=EV3_CH.	R/W
0526	EV3_CH	Channel number setting 1:CH1, 2:CH2, 3:CH3	R/W
0580	DI	DI setting flag 0:NON 1:FLW 2:RUN 3:HLD 4:ADV	R/W
05B0	MEM	1:EEP Program Memory 0:RAM Random Memory	R/W
0600	Out Actn	Output characteristic setting flag 0:Rev Act. 1:Dir Act	R/W
0601	Out Cyc	Control output cycle (Unit:0.5 seconds) Range: 0.5~120.0 seconds	R/W
0602	Reserved		
0603	SOFTSW	Soft start setting flag 0:OFF 1:ON	

0610	AT Point	AT pointer Range: 0~5000 unit	R/W
0611	Key Lock	0:OFF 1:LOCK1 2:LOCK2 3:LOCK3	R/W

- When Out_Cyc is written, writing data is adjusted to 0.5 sec as one unit.
- The write command lock by keylock is the same as the screen lock. (Refer to the manual of the instrument.)
- If there is a change in EV1_CH, EV2_CH, EV3_CH, the related parameters are initialized.

0701	PV Bias	PV bias Range: -1999~1999 unit	R/W
0702	PV Filt	PV filter Range: 0~100 seconds	R/W

0710	PFLW	Setting of CH2, CH3 PV input follow 0:OFF 1:ON	R/W
0711	CH_P	Selection of CH2, CH3 PV display or not 0-0 Window 0: Without 1: With	R/W

0800	FP_MOD	Selection between FIX and PROG 0:FIX 1:PROG (Writing possible only in CH1)	R/W
0801	PV_ST	Setting of PV start 0:OFF 1:ON (Writing possible only in CH1)	R/W

0882	STP	The number of steps 1~9 (Writing possible only in CH1)	R/W
0883	RPT	The number of execution repetitions 1~9999 (Writing possible only in CH1)	R/W
0884	ST_SV	Start SV (Writing possible only in CH1)	R/W

- For CH1, PFLW (window 1~30), CH_P (window1-29) display- - - -.The read value is: 7FFEh, To a write command, error (0BH) is returned.

08A0	Step1 SV	Step No. 1 SV Value (Writing possible only in CH1)	R/W
08A1	Step1 Time	Step No. 1 Step Time (Writing possible only in CH1)	R/W
08A2	Step1 PID No	Step No. 1 PID No.	R/W
08A3	Reserved		
08A4	Step2 SV	Step No. 2 SV Value (Writing possible only in CH1)	R/W
08A5	Step2 Time	Step No. 2 Step Time (Writing possible only in CH1)	R/W
08A6	Step2 PID No	Step No. 2 PID No.	R/W
08A7	Reserved		
08A8	Step3 SV	Step No. 3 SV Value (Writing possible only in CH1)	R/W
08A9	Step3 Time	Step No. 3 Step Time (Writing possible only in CH1)	R/W
08AA	Step3 PID No	Step No. 3 PID No.	R/W
08AB	Reserved		
08AC	Step4 SV	Step No. 4 SV Value (Writing possible only in CH1)	R/W
08AD	Step4 Time	Step No. 4 Step Time (Writing possible only in CH1)	R/W
08AE	Step4 PID No	Step No. 4 PID No.	R/W
08AF	Reserved		
08B0	Step5 SV	Step No. 5 SV Value (Writing possible only in CH1)	R/W
08B1	Step5 Time	Step No. 5 Step Time (Writing possible only in CH1)	R/W
08B2	Step5 PID No	Step No. 5 PID No.	R/W
08B3	Reserved		
08B4	Step6 SV	Step No. 6 SV Value (Writing possible only in CH1)	R/W
08B5	Step6 Time	Step No. 6 Step Time (Writing possible only in CH1)	R/W
08B6	Step6 PID No	Step No. 6 PID No.	R/W
08B7	Reserved		
08B8	Step7 SV	Step No. 7 SV Value (Writing possible only in CH1)	R/W

08B9	Step7 Time	Step No. 7 Step Time (Writing possible only in CH1)	R/W
08BA	Step7 PID No	Step No. 7 PID No.	R/W
08BB	Reserved		
08BC	Step8 SV	Step No. 8 SV Value (Writing possible only in CH1)	R/W
08BD	Step8 Time	Step No. 8 Step Time (Writing possible only in CH1)	R/W
08BE	Step8 PID No	Step No. 8 PID No.	R/W
08BF	Reserved		
08C0	Step9 SV	Step No. 9 SV Value (Writing possible only in CH1)	R/W
08C1	Step9 Time	Step No. 9 Step Time (Writing possible only in CH1)	R/W
08C2	Step9 PID No	Step No. 9 PID No.	R/W